Model Number

AVS58-H

Features

- **Industrial standard housing Ø58 mm**
- **16 Bit singleturn**
- **Hardware encoder**
- **Data transfer up to 2 MBaud**
- **Optically isolated RS 422 interface**
- **Servo or clamping flange**
- **Up to 4096 pulses on incremental track**

Description

This singleturn absolute encoder with modern fast technology transmits a position value corresponding to the shaft setting via the SSI interface (Synchronous Serial Interface). The resolution of the AVS58-H is maximum 65536 steps per revolution. In contrast to the AVS58 series the encoder does not have a microcontroller. Thus, it is a pure hardware encoder.

The control module sends a clock bundle to the absolute encoder to obtain the position data. The rotary encoder then sends the position data synchronous to the cycles of the control module. It is possible to select the counting direction with the function input.

This singleturn absolute encoder is available either in clamp flange design with a shaft diameter of 10 mm x 20 mm or in a servo flange design with a shaft diameter of 6 mm x 10 mm. The electrical connection is made by a 12-pin round plug connector. It is also possible to obtain a version with a 1 m cable connector.

Technical data

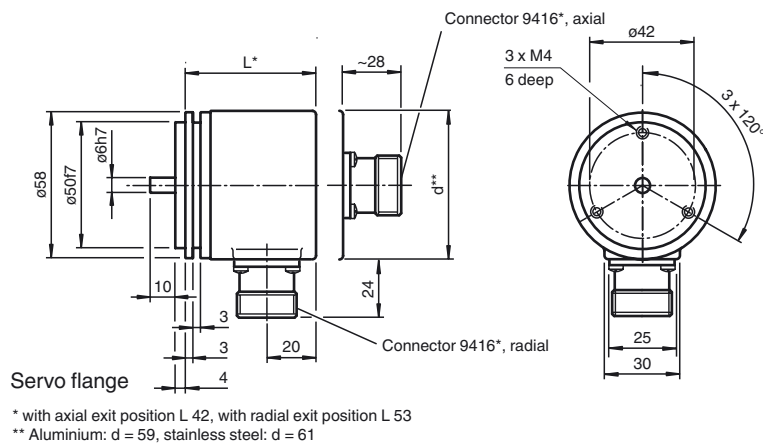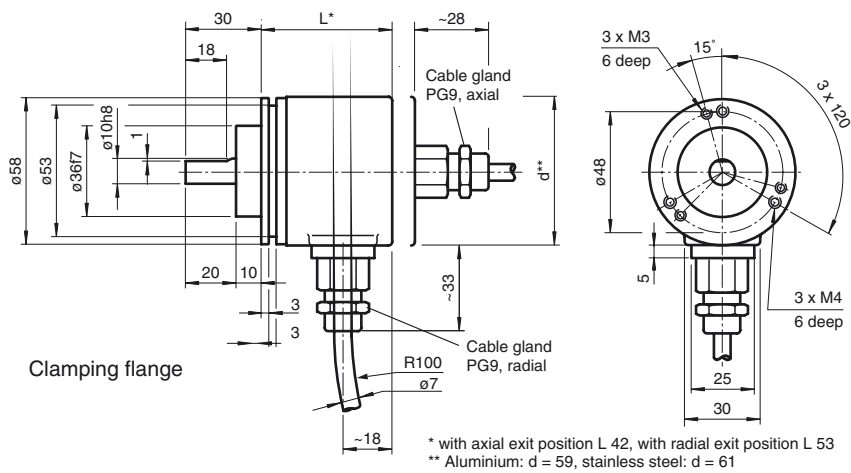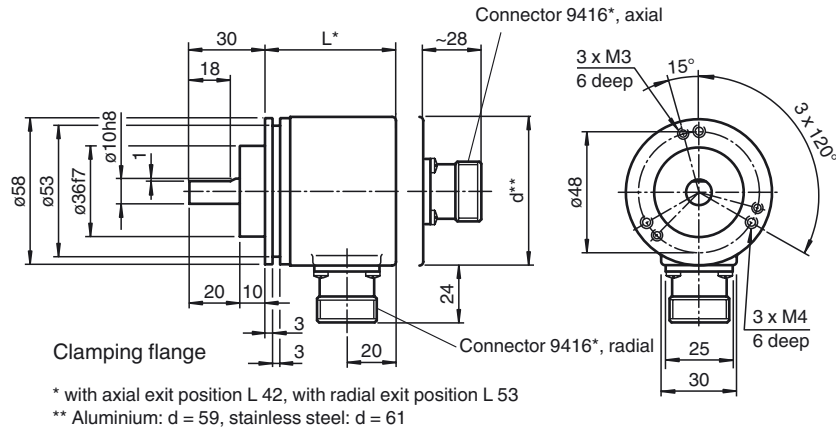| General specifications	
Detection type	photoelectric sampling
Device type	Singleturn absolute encoder
Functional safety related parameters	
$MTTF_d$	170 a
Mission Time (T_M)	20 a
L_{10h}	1.9 E+11 at 6000 rpm and 20/40 N axial/radial shaft load
Diagnostic Coverage (DC)	0 %
Electrical specifications	
Operating voltage U_B	4.5 ... 30 V DC (SSI, SSI + RS422) ; 10 ... 30 V DC (SSI + Push/Pull)
No-load supply current I_0	max. 180 mA
Time delay before availability t_v	< 250 ms
Linearity	± 2 LSB at 16 Bit, ± 1 LSB at 13 Bit, ± 0,5 LSB at 12 Bit
Output code	Gray code, binary code
Code course (counting direction)	cw descending (clockwise rotation, code course descending)
Interface	
Interface type	SSI ; SSI + incremental track
Monoflop time	20 ± 10 µs
Resolution	
Single turn	up to 16 Bit
Overall resolution	up to 16 Bit
Transfer rate	0.1 ... 2 MBit/s
Voltage drop	U_B - 2.5 V
Standard conformity	RS 422
Input 1	
Input type	Selection of counting direction (cw/ccw)
Signal voltage	
High	4.5 ... 30 V
Low	0 ... 2 V
Input current	< 6 mA
Switch-on delay	< 10 ms
Output	
Output type	RS422, Push/Pull
Signal output	A+B+/A+/B
Pulses	1024, 2048, 4096
Connection	
Connector	type 9416 (M23), 12-pin, type 9416L (M23), 12-pin
Cable	Ø7 mm, 6 x 2 x 0.14 mm², 1 m
Standard conformity	
Degree of protection	DIN EN 60529, IP65 (without shaft seal) ; DIN EN 60529, IP66/IP67 (with shaft seal)
Climatic testing	DIN EN 60068-2-3, no moisture condensation
Emitted interference	DIN EN 61000-6-4
Noise immunity	DIN EN 61000-6-2
Shock resistance	DIN EN 60068-2-27, 100 *g*, 6 ms
Vibration resistance	DIN EN 60068-2-6, 20 *g*, 10 ... 2000 Hz
Ambient conditions	
Operating temperature	-40 ... 85 °C (-40 ... 185 °F)
Storage temperature	-40 ... 85 °C (-40 ... 185 °F)
Mechanical specifications	
Material	
Combination 1	housing: powder coated aluminum flange: aluminum shaft: stainless steel
Combination 2 (Inox)	housing: stainless steel flange: stainless steel shaft: stainless steel
Mass	approx. 460 g (combination 1) approx. 800 g (combination 2)
Rotational speed	max. 12000 min⁻¹
Moment of inertia	50 gcm²
Starting torque	< 5 Ncm
Shaft load	
Axial	40 N
Radial	110 N

Approvals and certificates	
UL approval	cULus Listed, General Purpose, Class 2 Power Source

Refer to "General Notes Relating to Pepperl+Fuchs Product Information".

Pepperl+Fuchs Group
www.pepperl-fuchs.com

USA: +1 330 486 0001
fa-info@us.pepperl-fuchs.com

Germany: +49 621 776 4411
fa-info@de.pepperl-fuchs.com

Singapore: +65 6779 9091
fa-info@sg.pepperl-fuchs.com

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Dimensions

Connector 9416*, axial

3 x M3
6 deep

15°

3 x 120°

Clamping flange

Connector 9416*, radial

3 x M4
6 deep

* with axial exit position L 42, with radial exit position L 53
** Aluminium: d = 59, stainless steel: d = 61

Cable gland
PG9, axial

3 x M3
6 deep

15°

3 x 120°

Clamping flange

Cable gland
PG9, radial

R100
ø7

~18

3 x M4
6 deep

* with axial exit position L 42, with radial exit position L 53
** Aluminium: d = 59, stainless steel: d = 61

Connector 9416*, axial

ø42

3 x M4
6 deep

3 x 120°

Servo flange

Connector 9416*, radial

* with axial exit position L 42, with radial exit position L 53
** Aluminium: d = 59, stainless steel: d = 61

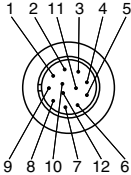Refer to "General Notes Relating to Pepperl+Fuchs Product Information".
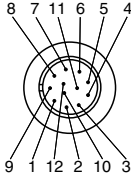
Pepperl+Fuchs Group
www.pepperl-fuchs.com

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fa-info@us.pepperl-fuchs.com

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L*

ø42

3 x M4
6 deep

3 x 120°

Cable gland
PG9, axial

ø58
ø50f7
ø6h7

d**

10

~33

5

3

3

Cable gland
PG9, radial

4

R100
ø7

25

Servo flange

30

~18

* with axial exit position L 42, with radial exit position L 53
** Aluminium: d = 59, stainless steel: d = 61

Refer to "General Notes Relating to Pepperl+Fuchs Product Information".

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Electrical connection

Signal	Cable Ø7 mm, 12-core	Connector 9416, 12-pin	Connector 9416L, 12-pin	Explanation
GND (encoder)	White	1	1	Power supply
U_b (encoder)	Brown	2	8	Power supply
Clock (+)	Green	3	3	Positive cycle line
Clock (-)	Yellow	4	11	Negative cycle line
Data (+)	Grey	5	2	Positive transmission data
Data (-)	Pink	6	10	Negative transmission data
A	Blue	7	12	Incremental track A
V/R	Red	8	5	Input for selection of counting direction
Reserved	Black	9	9	Not wired, reserved
B	Violet	10	4	Incremental track B
A	Grey/Pink	11	6	Incremental track $\overline{A}$
B	Red/Blue	12	7	Incremental track $\overline{B}$
		1 2 11 3 4 5 9 8 10 7 12 6	8 7 11 6 5 4 9 1 12 2 10 3	

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Description

The Synchronous Serial Interface was specially developed for transferring the output data of an absolute encoder to a control device. The control module sends a clock bundle and the absolute encoder responds with the position value.

Thus only 4 lines are required for the clock and data, no matter what the resolution of the rotary encoder is. The RS 422 interface is optically isolated from the power supply.

SSI signal course Standard

$D_1, ..., D_n$:	Position data
S:	Special bit
MSB:	Most significant bit
LSB:	Least significant bit

$T = 1/f$:	Duration of period of clock signal ≤ 1 MHz
T_m:	Monoflop time 10 µs ... 30 µs
T_p:	Clock pause $\geq$ monoflop time ($T_p \geq T_m$)
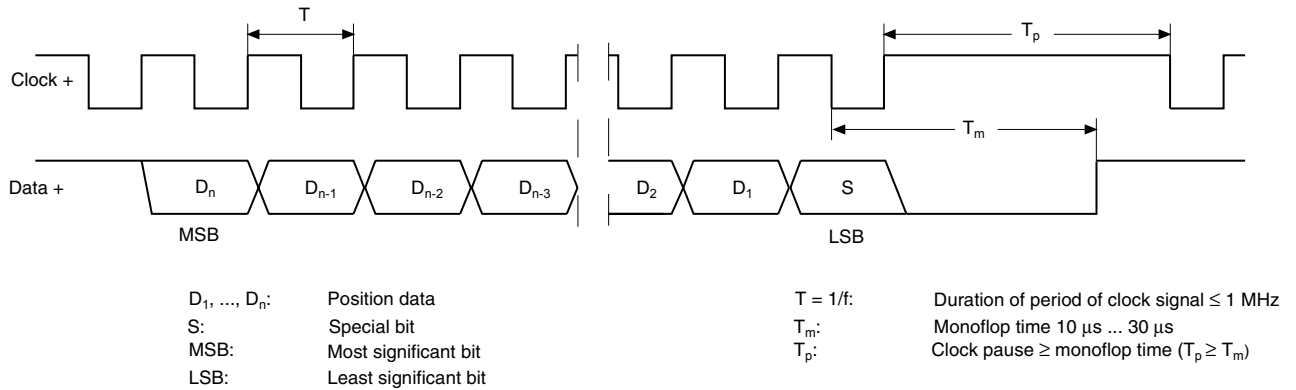
SSI output format Standard

- At idle status signal lines "Data +" and "Clock +" are at high level (5 V).
- The first time the clock signal switches from high to low, the data transfer in which the current information (position data (D_n) and special bit (S)) is stored in the encoder is introduced.
- The highest order bit (MSB) is applied to the serial data output of the encoder with the first rising pulse edge.
- The next successive lower order bit is transferred with each following rising pulse edge.
- After the lowest order bit (LSB) has been transferred the data line switches to low until the monoflop time T_m has expired.
- No subsequent data transfer can be started until the data line switches to high again or the time for the clock pause T_p has expired.
- After the clock sequence is complete, the monoflop time T_m is triggered with the last falling pulse edge.
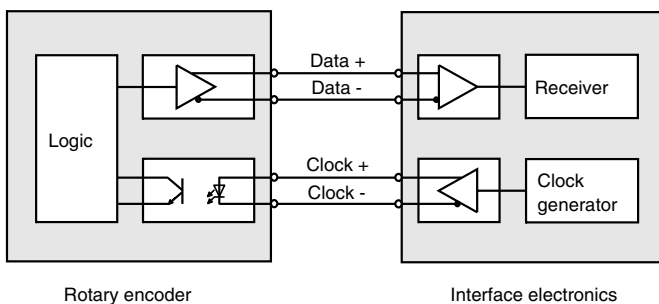- The monoflop time T_m determines the lowest transmission frequency.

SSI output format ring slide operation (multiple transmission)

- In ring slide operation, multiple transmission of the same data word over the SSI interface makes it possible to offer the possibility of detecting transmission errors.
- In multiple transmission, 25 bits are transferred per data word in standard format.
- If the clock change is not interrupted after the last falling pulse edge, ring slide operation automatically becomes active. This means that the information that was stored at the time of the first clock change is generated again.
- After the first transmission, the 26th pulse controls data repetition. If the 26th pulse follows after an amount of time greater than the monoflop time T_m, a new current data word will be transmitted with the following pulses.

⚠ If the pulse line is exchanged, the data word is generated offset.
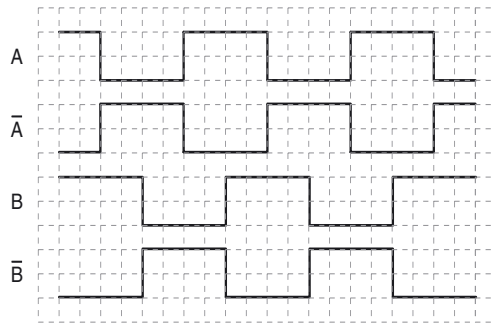Ring slide operation is possible up to max. 13 bits.

Block diagram

Rotary encoder   Interface electronics

Line length

Line length in m	Baudrate in kHz
< 50	< 400
< 100	< 300
< 200	< 200
< 400	< 100

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Signal outputs

A

$\overline{A}$

B

$\overline{B}$
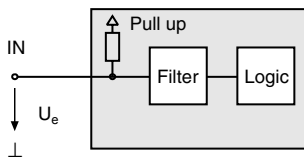
↻ cw - with view onto the shaft

Input

The selection of the counting direction input (V/R) is activated with 0-level.

IN

Pull up

Filter

Logic

U_e

⊥

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Accessories

For type	Accessories	Name/defining feature	Order code
AVS58*-011	Couplings	D1: Ø10 mm, D2: Ø10 mm	9401
		D1: Ø10 mm, D2: Ø10 mm	9404
		D1: Ø10 mm, D2: Ø10 mm	9409
		D1: Ø10 mm, D2: Ø10 mm	KW
	Measurement wheels with circumference of 500 mm	Plastic	9101, 10
		Pimpled rubber	9102, 10
		Knurled aluminium	9103, 10
		Knurled plastic	9112, 10
	Measurement wheels with circumference of 200 mm	Plastic	9108, 10
		Pimpled rubber	9109, 10
		Knurled aluminium	9110, 10
		Knurled plastic	9113, 10
	Mounting aids	Mounting bracket	9203
		Mounting bracket	9213
AVS58*-032	Couplings	D1: Ø6 mm, D2: Ø6 mm	9401
		D1: Ø6 mm, D2: Ø6 mm	9402
		D1: Ø6 mm, D2: Ø6 mm	9404
		D1: Ø6 mm, D2: Ø6 mm	9409
		D1: Ø6 mm, D2: Ø6 mm	KW
	Mounting aids	Mounting bracket and set	9300 and 9311-3
		Eccentric clamping elements	9310-3
All	Connectors	Cable socket	9416
		Cable socket	9416L

For additional information on the accessories, please see the "Accessories" section.

Refer to "General Notes Relating to Pepperl+Fuchs Product Information".

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Order code

```
A  V  S  5  8  ─  ☐  ☐  ☐  ☐  ☐  H  ☐  ─  0  0  ☐  ☐
```

Number of bits singleturn
12   4096 (standard)
13   8192
16   65536

Options
1   Incremental track 1024 pulses, Push/Pull
2   Incremental track 2048 pulses, Push/Pull
3   Incremental track 4096 pulses, Push/Pull
4   Incremental track 1024 pulses, RS422
5   Incremental track 2048 pulses, RS422
6   Incremental track 4096 pulses, RS422

Output code
B   Binary
G   Gray

Exit position
A   Axial
R   Radial

Connection type
K1   Cable Ø7 mm, 6 x 2 x 0.14 mm², 1 m
AA   Plug connector type 9416, 12-pin
AB   Plug connector type 9416L, 12-pin

Shaft dimension/flange version
011   Shaft Ø10 mm x 20 mm with clamping flange
032   Shaft Ø6 mm x 10 mm with servo flange

Housing material
N   Aluminium, powder coated
I   Inox*

Principle of operation
S   Singleturn

Shaft version
V   Solid shaft

Data format
A   SSI (Synchronous Serial Interface)

*Housing material I only available with axial exit position.

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